









Robot i series

Cost Savings through Intelligent Robotization for the 21st Century

GENERAL CATALOG

FANUC

Advantage of using robots

• FANUC Robots will provide your factories with a wide range of advantages.

Increased Productivity

- Robots are able to handle products that are too heavy and unsafe for humans to lift.
- Robots are able to operate faster than humans.
- Robots can work nights, weekends, holidays, and in "lights out" facilities without a rest.

Higher Product Quality

- Robots are more accurate than manual labor.
- Robots provide higher product quality more consistently than manual labor.

Improved Work Reliability

- Robots are highly durable and can be relied on for a long-term operation.
- Robots are able to perform complex tasks and operations on behalf of humans.
- No sudden surprises such as sick leave or retirement exists.

Reduced Costs

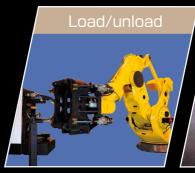
- Replacing manual operations with robots can reduce personnel costs.
- Easier system or process changeover can be realized.





Various application of robots

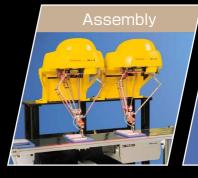
- FANUC has a wide range of robot types and models available for various applications.
- Various features are available for FANUC robots to make a maximum use of robot flexibilities.

























FANUC Robot i series



















R-3*1* A

Collaborative Robot

			i			
FANUC Robot CRX		10 <i>i</i> A		10 <i>i</i> A/L		
> X	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application	1240mm, 24	R-	6 10kg Inge) 14 ±0.04mm 40kg DOR, Upside-down, A 30/B Mini Plus/1.5	kVA	
FANUC Robot CR-	4 <i>i</i> A, 7 <i>i</i> A, 14 <i>i</i> A	4iA	7iA	7iA/L	1 <i>4i</i> A/L	
FANUC Robot CR-	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application	4kg 550mm, 818mm 48kg R-30iB Mate/R-30	iB Mate Plus(standard	911mm, 1359mm ±0.01mm por, Upside-down, A	R-30iB Mate Plus(standard)/1.2kVA	
	Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application		R-30iB Plus (A-cabi	15kg 1441mm, 2413mi ±0.02mm 255kg oor, Upside-down, A net), R-30 <i>i</i> B Mate I Handling, Assembli	ngle Plus (standard)/2kVA	
FANUC Robot CR-	35iA 6 35kg 1813mm, 2931mm ±0.03mm 990kg Floor R-30iB/R-30iB Plus(A-cabinet)/3kVA Handling, Assembling					

Mini Robot, SCARA Robot

		,						
FANUC Robot LR N	200 <i>i</i> D	/7L	/4S	/1-	4L			
FANUC Robot ARC	50 <i>i</i> D	//L						
FANUC Robot ER-4	ı <i>i</i> A						ER-4 <i>i</i> A	
	Controlled axes			6	3			
	Max.payload at wrist	7	kg	4kg		kg.	4kg	
	Motion range(X,Y)	717mm, 1274mm	911mm, 1643mm	550mm, 970mm	911mm (load capaci 820mm (load capaci	ity<12kg), 1643mm ity≧12kg), 1643mm	550mm, 970mm	
	Repeatability Mass	25kg	27kg	±0.0 20kg	1mm 27	'ka	20kg	
	Installation	LUKE		r, Upside-down, A		N5	Floor, Upside-down	
	Matching controller/Input power source capacity	B-30/B Mate/B-30	IB Mate Plus (standar		R-30;R Mate F	Plus(standard, or		
	Handling	•	•	•	THOUSE MIGRO		•	
	Assembling	Ŏ	Ŏ	Ŏ			Ŏ	
	Application Arc welding	•	•	•				
X	Sealing	•	•	•				
	Others		Mold re	elease spray, Del	burring			
FANUC Robot LR N	Nate 200 <i>i</i> D	/7WP		/7C	/7LC		/7H	
	Controlled axes			6			5	
	Max.payload at wrist			71	(g		_	
	Motion range(X,Y)					911mm, 1643mm 717mi		
	Repeatability			±0.0	±0.01mm			
	Mass		25kg		27kg		24kg	
	Installation	D 00.5			-down, Angle		(1. OL) (1.	
	Matching controller/Input power source capacity	H-30iE	Mate(standard,	open air)/R-30il	3 Mate Plus(star	ndard, open air)	/1.2kVA	
	Handling	•						
	Application Assembling Washing				•			
- X	Clean room			•				
	Olcul 10011							
FANUC Robot SR-3	B <i>İ</i> A, 6 <i>İ</i> A, 12 <i>İ</i> A, 20 <i>İ</i> A	SR-3iA	SR-3iA/H	SR-6 <i>i</i> A	SR-6iA/H	SR-12 <i>i</i> A	SR-20 <i>i</i> A	
	Controlled axes	4	3	4	3		4	
Max.payload at wrist Motion range(X,Y)		3	kg	61		12kg	20kg	
			, 800mm		1300mm		1100mm, 2200mm	
	Stroke(Z) J1+J2 axis	200	Omm	21C)mm	±0.015mm	tion:450mm) ±0.02mm	
	Repeatability J3 stroke		±0.0	±0.0	1 mm	±0.0 15111111	±0.0211111	
	J4 axis	±0.004°		±0.004°	1111111	+0	.005°	
	Mass	19kg	17kg	30kg	28kg	53kg	64kg	
	Installation	IONE	1716	Floor		COKE	O-Mg	
X	Matching controller/Input power source capacity							
	Application			Handling, A				



Delta Robot

	/O.F.A	(0.50	/111	/O.E.A.I	(O.F.O.)	/11.11	
FANUC Robot M-11A		/0.5A	/0.5S	/1H	/0.5AL	/0.5SL	/1HL
	Controlled axes	6	4	3	6	4	3
	Max.payload at wrist		tion:1kg)	1kg		ntion:1kg)	1kg
	Motion range(X,Y)	g.	280mm, 100m			6420mm, 150mi	n
	Repeatability			±0.0			
	Mass(without stand)	17kg	14kg	12kg	20kg	17kg	15kg
	Installation	D 00 I	2.14 . /0		ing, Angle		(31)/4
	Matching controller/Input power source capacity	H-301	Nate (Standard	d, open air)/R-30	B Mate Plus(St	andard, open air)	/ IKVA
- ^ - 	Application Handling Assembling		•	•		•	•
FANUC Robot M-2	iΔ	/3A	/35	/6H	/3AL	/3SL	/6HL
	Controlled axes	6	4	3	6	4	3
1 5 2	Max.payload at wrist		Kg -	6kg		kg	6kg
5	Motion range(X.Y)		800mm. 300m			1130mm, 400m	
1 \(\frac{1}{2} - 77\)	Repeatability	,		±0.0			
l \//	Mass	140kg	130kg	125kg	140kg	130kg	125kg
	Installation				ling		
	Matching controller/Input power source capacity	R-30iB/R-30iB P	lus(A-cabinet), R-3	DiB Mate(standard, open air)/R-30iB Mate Plus(standard, open air)/12			
_ X _	Application Handling	•	•	•	•	•	•
	Assembling				_		
FANUC Robot M-3	•	/6	SA	/6	SS	/1	2H
FANUC Robot M-3	•		SA S		5S		2H 3
FANUC Robot M-3	iA	(1	(
FANUC Robot M-3	Controlled axes Max.payload at wrist Motion range(X,Y)	(3	6kg(opt φ1350mr	1 ion:8kg) n, 500mm	(3
FANUC Robot M-3	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability	6	S Kg	6kg(opt φ1350mr ±0.0	1 ion:8kg) n, 500mm 3mm	12	3 Pkg
FANUC Robot M-3	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass	6	3	6kg(opt \$\phi\$1350mr \$\pm\$0.0	1 ion:8kg) n, 500mm 3mm Okg	12	3
FANUC Robot M-3	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation	6	5 Kg 5kg	6kg(opt φ1350mr ±0.0 160 Cei	ion:8kg) n, 500mm 3mm Okg	12	3 2kg 5kg
FANUC Robot M-3	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity	6	5 Kg 5kg	6kg(opt \$\phi\$1350mr \$\pm\$0.0	ion:8kg) n, 500mm 3mm Okg	12	3 2kg 5kg
FANUC Robot M-3	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Handling	6	5 Kg 5kg	6kg(opt φ1350mr ±0.0 160 Cei	ion:8kg) n, 500mm 3mm Okg	12	3 2kg 5kg
FANUC Robot M-3	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity	6	5 Kg 5kg	6kg(opt φ1350mr ±0.0 160 Cei	ion:8kg) n, 500mm 3mm Okg	12	3 2kg 5kg
FANUC Robot M-3 FANUC Robot DR-3	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Handling Assembling 31B	6	5 Kg 5kg	6kg(opt)	4 ion:8kg) n, 500mm 3mm Okg ling open air)/R-30 <i>i</i> B N	12	3 2kg 5kg
×	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Handling Assembling 31B Controlled axes	6	5 Kg 5kg	6kg(opt \$\phi\$1350mr \$\pmu\$1350mr \$\pmu\$0.0 16f Cei 0/B Mate(standard,	4 ion:8kg) n, 500mm 3mm Okg ling open air)/R-30iB N	12	3 2kg 5kg
×	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Application Assembling Controlled axes Max.payload at wrist	6	5 Kg 5kg	Gkg(opt) Ø1350mr ±0.0 166 Cei O/B Mate(standard,	4 ion:8kg) n, 500mm 3mm Okg ling open air)/R-30iB N	12	3 2kg 5kg
×	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Handling Assembling Controlled axes Max.payload at wrist Motion range(X,Y)	6	5 Kg 5kg	6kg(opt) \$\phi\$1350mr \$\pm 1350mr \$\pm 10.0 \$\pm 1600mr \$\pm 1600mr \$\pm 16kg(opt) \\ \$\pm 16kg(opt)	4 ion:8kg) ion:8kg) n, 500mm 3mm Okg ling open air)/R-30iB N BL 4 kg n, 500mm	12	3 2kg 5kg
x	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Handling Assembling 3 iB Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability	6	5 Kg 5kg	6kg(opt \$\phi\$1350mr \(\phi\$0.00\) 166 Cei 0/B Mate(standard.) //E 88 \$\phi\$1600mr \(\phi\$0.00\)	4 ion:8kg) n, 500mm 3mm Okg ling open air)/R-30iB N BL 4 kg n, 500mm 3mm	12	3 2kg 5kg
x	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Application Handling Assembling Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass	6	5 Kg 5kg	6kg(opt) \$\phi\$1350mr \$\pm 1350mr \$\pm 10.0 \$166 \$Cei 0/B Mate(standard, /\ell \$\frac{\pm 1600mr}{\pm 1600mr} \$\pm 10.0 \$\pm 17	4 ion:8kg) n, 500mm 3mm Okg ling open air)/R-30iB N BL 4 kg n, 500mm 3mm Okg	12	3 2kg 5kg
x	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Assembling Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation	6	SKg 5kg lus(A-cabinet), R-3	6kg(opt \$6kg(opt) \$40.0 166 Cei 0/8 Mate(standard, /8 8 \$1600mr \$\pm0.0 177 Cei	4 ion:8kg) n, 500mm 3mm Okg ling open air)/R-30iB N BL 4 sg n, 500mm 3mm Okg ling	15 15 Mate Plus(standard	3 2kg 5kg
×	Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Application Handling Assembling Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass	6	SKg 5kg lus(A-cabinet), R-3	6kg(opt) \$\phi\$1350mr \$\pm 1350mr \$\pm 10.0 \$166 \$Cei 0/B Mate(standard, /\ell \$\frac{\pm 1600mr}{\pm 1600mr} \$\pm 10.0 \$\pm 17	4 ion:8kg) ,,,500mm 3mm Dkg ling open air)/R-30/B N 8 4 4 4 5 7 8 7 8 8 7 8 8 8 8 9 8 8 8 9 8 8 8 8 8	15 15 Mate Plus(standard	3 2kg 5kg

Arc Welding Robot, Small/Medium Size Robot

Repeatability Mass Installation Matching controller/Input power source capacity Handling Application FANUC Robot ARC Mate 120 iD FANUC Robot M-20 iD Controlled axes Max payload at wrist Mass Installation Matching controller/Input power source capacity Handling Arc welding Sealing Others M-20 iD/25 ARC Mate 120 iD M-20 iD/25 M-20 iD/25 ARC Mate 120 iD M-20 iD/25 M-20 iD/25 ARC Mate 120 iD M-20 iD/25 M-20 iD/25 ARC Mate 120 iD M-20 iD/25 M-20 iD/25 ARC Mate 120 iD ARC Mate 120 iD M-20 iD/25 ARC Mate 120 iD										
Controlled axes	FANUC Robot ARC	Mate 100 <i>i</i> D		/100	ARC	Mate 100iD	/101		/OI	
Controlled axes Max.psyload at wrist Mothers and Paperate District Controlled axes Max.psyload at wrist Max.psyload at wrist Mass Installation Application FANUC Robot M-20iB Application FANUC Robot M-20iB Application Application FANUC Robot M-20iB Application Applicat	FANUC Robot M-101D			/165	M-	10 <i>i</i> D/12	/ TUL		/8L	
Max.peyload at wrist 16kg 12kg 10kg 8kg 203zmm, 376zmm 140.0zmm 16.6mm 16.6mm, 3006mm 203zmm, 376zmm 14.5kg 16.5mm, 3006mm 203zmm, 376zmm 14.5kg 15.0kg	Traited Hobel III Ie					F	3			
FANUC Robot ARC Mate 120 iD FANUC Robot M-20 iD Controlled axes Max, payload at wrist Mass Installation Application		Motion range(X,Y) Repeatability Mass Installation		1103mm, 1977mm ±0.0 145 Floo	2mm 5kg or. Upsid	mm, 2616mm e-down. Angle *	1636mm, 300 150kg Floor, Upside-dov	±0.03	2032mm, 3762mm Bmm 180kg BK	
FANUC Robot ARC Mate 120 <i>i</i> D FANUC Robot M-20 <i>i</i> D Controlled axes Mex.payload at wrist Mass Installation Matching controlled axes Max.payload at wrist Motion range(X,Y) Application FANUC Robot M-20 <i>i</i> B Application Applic		Application Hand Asse Application Sealing	lling mbling velding ng	H-3U/B	Plus(A-,			andard)	/ZKVA	
Controlled axes		•		ADC Mate 100	·D	Wicia Harianii	B, Deburring			
Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Application Applicati		•			10	/3	35		/12L	
Max,payload at wrist Motion range(X,Y) 1831mm, 3461mm 1831mm, 3461mm 2272mm, 4343mm 2272mm, 4343mm 2272mm, 4343mm 1831mm, 3461mm 2272mm, 4343mm 2272mm, 4343mm 2272mm, 4343mm 2500mm 250kg Mass Floor, Upside-down, Angle Floor, Upside-down, Angle Floor, Upside-down, Angle Floor, Upside-down, Angle Floor, Upside-down, Angle Assembling Application Are welding Sealing Mold handling, Deburring Floor, Upside-down, Angle Skg Max,payload at wrist Motion range(X,Y) 1853mm, 3345mm 1445mm, 2591mm 1445mm, 2591mm 1445mm, 2591mm 1500r, Upside-down, Angle R-30/iB/R-30/iB Plus (A, B-cabinet), R-30/iB Mate/R-30/iB Mate Plus (standard)/3kVA R-30/iB Mate/R-30/iB Mate Plus (standard)/3kVA Mate Plus (standard)/3	FANUC Robot M-20			M-201D/25						
Matching controller/Input power source capacity Handling Application Application FANUC Robot M-20iB Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Respectability Mass Installation Matching controller/Input power source capacity Handling Application Matching controller/Input power source capacity Handling Application Matching controller/Input power source capacity Application Matching controller/Input power source capacity Application Matching controller/Input power source capacity Mass Installation Application Application Application Matching controller/Input power source capacity Mass Application Application Matching controller/Input power source capacity Mass Application Application Matching controller/Input power source capacity Application Matching controller/Input power source capacity Application Application Matching controller/Input power source capacity Application Application Matching controller/Input power source capacity Application Application Matching controller/Input power source capacity Application Application Matching controller/Input power source capacity Application Application Matching controller/Input power source capacity Application Application Matching controller/Input power source capacity Application Application Application Application Matching controller/Input power source capacity Application		Max.payload at wris Motion range(X,Y) Repeatability	t	1831mm, 3461mm		35kg 1831mm, 3461mm ±0.0		2272mm, 4343mm		
Application Arc welding Sealing Others Mold handling, Deburring FANUC Robot M-201B Controlled axes 6 Max.payload at wrist Motion range(X,Y) Repeatability Repeatability Mass Installation Matching controller/Input power source capacity Application Application Application Application Application Arc welding Assembling Arc welding Sealing Clean room Application Application Application Arc welding Sealing Clean room Mold handling, Deburring //25 //25C //35S //25C //35S //25C //35S //25C //35S //25C //35S //25C //35S //25C //35S //25C //35S //25C //35S //25C //35S //35S //25C //35S //35S //25C //35S /		Matching controller/Inpu Hand	lling	R-30 <i>i</i> B	Plus(A-,	Floor, Upside , B-cabinet), R-3	-down, Angle OiB Mate Plus(st	andard).	/3kVA	
Controlled axes Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Application Controlled axes 25kg 35kg 35kg 35kg 40.02mm 20.02mm Floor, Upside-down, Angle R-30iB/R-30iB Plus(A-, B-cabinet), R-30iB Plus(A-, B-cabinet), R-30iB Plus(A-, B-cabinet), R-30iB Plus(A-, B-cabinet), Mate Plus(standard)/3kVA Assembling Arc welding Sealing Clean room	X	Application Arc w Seali	velding ng	•		Mold handlin	g, Deburring			
Max.payload at wrist Motion range(X,Y) Repeatability Mass Installation Matching controller/Input power source capacity Application Application Max.payload at wrist 1853mm, 3345mm 1445mm, 2591mm 14	FANUC Robot M-20	oiB		/25		/2!	5C		/35S	
Matching controller/Input power source capacity Handling Assembling Application Application Application Matching controller/Input power source capacity R-30 <i>i</i> B/R-30 <i>i</i> B Plus(A-, B-cabinet), R-30 <i>i</i> B Plus(A-, B-cabinet), R-30 <i>i</i> B Plus(A-, B-cabinet), R-30 <i>i</i> B Plus(A-, B-cabinet), Mate Plus(standard)/3kVA Application Clean room		Max.payload at wrist Motion range(X,Y) Repeatability		18	25kg 1853mm, 3345mm ±0.02r			35kg 1445mm, 2591mm 2mm		
Application Application Application Assembling Arc welding Sealing Clean room	<u> </u>	Matching controller/Inpu		R-30 <i>i</i> B/R- R-30 <i>i</i> B Mate/R-3	-30 <i>i</i> B Pl 30 <i>i</i> B Ma	us(A-, B-cabinet),			
Others Mold handling, Deburring Mold handling, Deburring		Application Asse Arc w Sealii Clear	embling velding ng n room	Mold handling Dahir	rring			Mold	handling Dahurring	



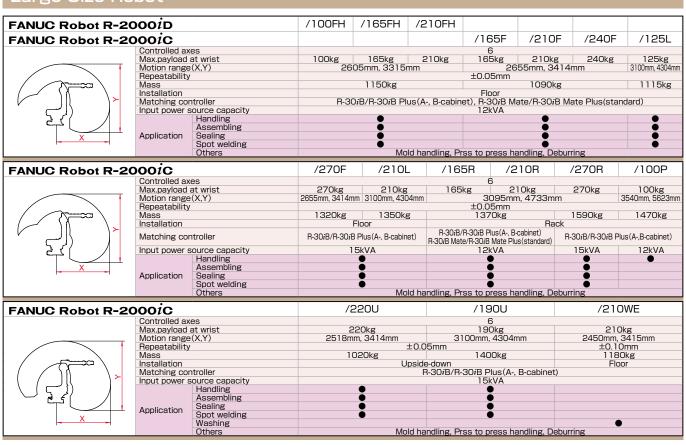
Arc Welding Robot, Small/Medium Size Robot

FANUC Robot M-71	FANUC Robot M-710 C			/50	/70	/12L	/20L	/20M	/50S	/50H
	Controlled ax	es				6				5
	Max.payload	at wrist	45kg	50kg	70kg	12kg	20kg	20kg	50kg	50kg
	Motion range	(X,Y)	2606mm, 4575mm	2050mm,	3545mm	3123mm, 5609mm	3110mm, 5583mm	2582mm, 4609mm	1359mm, 2043mm	2003mm, 3451mm
	Repeatability	• • •	±0.06mm	±0.03mm	±0.04mm		±0.06mm		±0.0	3mm
	Mass		570kg	56	Okg	540	Okg	530kg	545kg	540kg
	Installation				Floor, I	Jpside-down	, Angle			Floor, Upside-down
	Matching contro	ller/Input power source capacity	R-30 <i>i</i> E	7/R-30iB Plu	s(A-, B-cabir	net), R-30iB	Mate/R-30i	B Mate Plus	(standard)/	12kVA*
		Handling	•				•			
		Assembling	•	•	•	•	•	•	•	
I	Application	Arc welding	•	•	•	•	•	•	•	
	Application	Sealing	•	•	•	•	•	•	•	
× X >		Spot welding	•	•	•				•	
		Others		N	old handling	g, Deburring,	Laser cuttin	g		
		<u>'</u>								

* R-30iB Mate/R-30iB Mate Plus controller (standard) is not available for /50 H

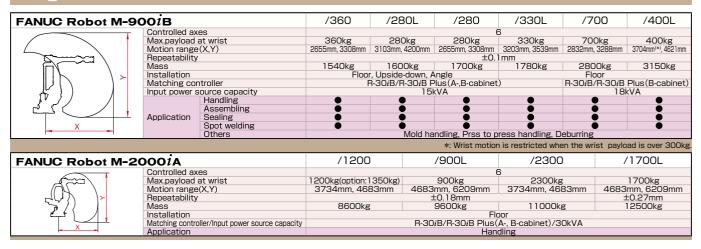
	* H-3U/B Mate/H-3U/B Mate Plus controller (standard) is not available for						
FANUC Robot M-8	00 <i>i</i> A	/60					
	Controlled axes			6			
	Max.payload at wrist			60kg			
	Motion range(X,Y)		í	2040mm, 3221mm	n		
	Repeatability			±0.015mm			
' 작/ /	Mass			820kg			
	Installation			Floor			
	Matching controller/Input power source capacity	·	R-30 <i>i</i> B	Plus(A-, B-cabinet)	/12kVA		
- ^ -	Application			Laser machining			
	!-	(005	(1005	(1.005	(100E 7D	(0011	
FANUC Robot R-10	000 <i>1</i> A	/80F	/100F	/130F	/120F-7B	/80H	
	Controlled axes	6 7					
	Max.payload at wrist	80kg	100kg	130kg	120kg	80kg	
7	Motion range(X,Y)		2230mm, 3738mm		2230mm, 3779mm	2230mm, 3465mm	
	Repeatability		±0.03mm				
	Mass	620kg	665kg	675kg	790kg	610kg	
	Installation			Floor, Upside-down			
	Matching controller		lus(A-, B-cabinet), Mate Plus(standard)	R-30 <i>i</i> B	R-30iB/R-30iB Plus(A-, B-cabinet)		
	12	κVA	15	kVA	12kVA		
I \	Handling	•		•	•		
	Application Assembling						
Y	Sealing						
- ^ -	Spot welding	•	•		•		

Large Size Robot





Large Size Robot



Palletizing Robot, Others

FANUC Robot M-41	o <i>i</i> c	/110		/185 /315 /500				
FANUC Robot M-41	о <i>і</i> в		/140H	-1			/700	
~~~	Controlled axes	4	5			4		
	Max.payload at wrist	110kg	140kg	185kg	315kg	500kg	700kg	
	Motion range(X,Y)	2403mm, 2238mm	2850mm, 3546mm	m 3143mm, 2958mm				
(K-) (	Repeatability				±0.05mm			
ا العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العام العا	Mass	1030kg	1200kg	Pedestal type 1600kg	1) No pedestal 1330kg(#2)	Pedestal type 2410kg(+1) No pedestal 1910kg(+2)	2700kg(*1)	
	Installation				Floor			
		ty R-30iB Plus(A-, B-cabinet)/15kVA R-30iB/R-30iB Plus(A-, B-cabinet)/15kVA						
~ ^ >	Application				Handling			

^{*1:}Controller mass(120kg) is included. *2:Controller mass(120kg) is not included.

## Paint Robot

FANUC Robot P-4	0 <i>і</i> А, 350 <i>і</i> А, 250 <i>і</i> В	P-40 <i>i</i> A	P-350 <i>i</i> A/45	P-250 <i>i</i> B/15			
	Controlled axes		6	'			
	Max.payload at wrist	5kg	45kg	15kg			
	Motion range(X,Y)	1300mm, 2308mm	2606mm, 4575mm	2800mm, 5272mm			
I (	Repeatability	±0.03mm	±0.06mm	±0.2mm			
\	Mass	110kg	590kg	530kg			
	Installation		Floor, Upside-down, Wall, Rack, Angle				
	Matching controller/Input power source capacity	R-30iB Mate Plus / 1.5kVA	R-30iB Plus (A-cabinet) / 12kVA	R-30iB (A-cabinet) / 12kVA			
- X -	Application	Painting					
	•						
FANUC Robot P-10	000 <i>1</i> A	P-1000 <i>i</i> A					
	Controlled axes	7					
	Max.payload at wrist	10	kg(1500mm/s), 15kg(1200mm	/s)			
	Motion range(X,Y)		3348mm, 4343mm				
	Repeatability		±0.5mm				
/ لا	Mass		700kg				
	Installation		Wall				
	Matching controller/Input power source capacity	R-30iB (A-cabinet) / 12kVA					
- X	Application	Painting					

# Features of FANUC Robot

High Efficiency



Support Various Applications

# High Reliability

#### Reliable

FANUC designs and manufacturers all robot components with the highest quality and durability, including mechanical arms, servo motors, controllers, software, and sensors.

#### Predictable

Diagnostic features can inform you of conditions in which a robot may fail, allowing for preventative maintenance on the robot before a failure.

# High Efficiency

#### Learning Robot

The Learning Robot provides smooth and high-speed motion by suppressing robot vibration. This enhances the robot's productivity and the efficiency of a production line, which contributes to reduced overall system costs. Also the Learning Robot enhances the performance of handling a heavy

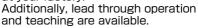


jig or workpiece, which causes robot vibration.

# Support Various Applications

#### Collaborative Robot

The collaborative robot immediately and safely stops when it comes in contact with a human operator, allowing for safe operation in the same workspace without safety fences. This provides production efficiency and cost savings on labor at your factory.

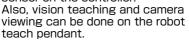




#### IRVision - Integrated Robot Vision

Vision hardware is integrated in the robot controller as standard. 2D compensation, 3D compensation, color sorting, error proofing, bar code reading, etc. can be realized just by connecting Camera or 3D sensor on the controller.

Also, vision teaching and camera





### Bin Picking

The Bin Picking Robot equipped with a vision sensor automates the picking process of randomly piled parts in a bin. The parts do not need to be arranged in advance, eliminating the need for positioning fixtures. It also allows for easy part changeover. The Bin Picking Robot enables unmanned part handling in your factories.



#### Zero Down Time

Zero Down Time combines various functions useful for preventive maintenance and helps to improve production efficiency by controlling these functions from a centralized server. This allows failures to be "Predictable".



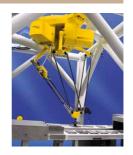


#### Easy to Repair

- · Robot mechanical units are designed for easy maintenance.
- Diagnostic features can estimate causes of failure, assisting your quick repair.

#### Visual Tracking

Through Visual Tracking the robot tracks and picks parts moving on a conveyor by utilizing the vision sensor located upstream. Multiple robots connected via a network can automatically divide the workload among the robots, allowing for automation in various picking and packing processes.



#### **Network Function**

OPC UA, MTConnect, Modbus communication etc. are supported. PC and PLC etc. can input/output robot data.



#### Force Sensor/Deburring-Polishing

The Six-Axis Force Sensor, equipped on the robot's wrist, enables a contouring motion of the robot tool while maintaining a designated pushing force to the part. The force-controlled robot contributes to automating processes such as deburring of machined part edges and polishing of part surfaces.



#### **ROBOGUIDE**

ROBOGUIDE is a powerful PC simulation software providing system layout, programming and accurate simulation tools for design and evaluation of various robot systems.



# Controller

	D 00:D /D 00:D	Divo Controllor		D 20:D Mata/D 20:D	Moto Divo Controllor			
		Plus Controller	R-30iB Mini Plus		Mate Plus Controller	R-30iB Compact		
	A-Cabinet	B-Cabinet	Controller	Standard Type	Open Air Type	Plus Controller		
		# d 0	C i			00.71		
Rated Supply Voltage	AC 200-575\ 50/60Hz ±1H		NRTL(UL1740) 110-120VAC +10%, -15% 200-240VAC +10%, -15% Except NRTL(IEC60204-1) 100-120VAC +10%, -10% 200-240VAC +10%, -15% 50/60Hz ±1Hz 1-phase	AC 200–230V - 50/60Hz ±1Hz,	+10% -15% 1-phase/3-phase	AC 200-240V +10% -15% 50/60Hz ±1Hz, 1-phase		
Mass of Controller	120-140kg	180-200kg	20kg	40kg	20kg	9kg		
Dimensions (W×D×H)	600x470x500	740x550x1100	410x277x370	470x322x400 470x402x400 *1	370x350x200 370x350x356 *1	440x260x85.5		
Overvoltage Category / Pollution degree		Overvoltage Pollution IEC60664-1, IE			Overvoltage Category II, Pollution Degree 2, *3 IEC60664-1, IEC/UL61010-1	Overvoltage Category II,II,*4 Pollution Degree 2,*3 IEC60664-1,IEC/UL61010-1		
Protection Class	IP54 IP20							
Emergency stop	Emergency stop function PL=e, Cat4(IS013849-1) SIL3(IEC61508) Position/Speed check function PL=d, Cat3(IS013849-1) SIL2(IEC61508)							
External Memory	USB, F	CMCIA	USB					
Fieldbus	FL-net, DeviceNet, F CC-Link IE, EtherNe	PROFIBUS, PROFINE t/IP, EtherCAT	ROFIBUS, PROFINET, EtherCAT upports CC-Link IE.	FL-net, DeviceNet, PROFIBUS, PROFINET, CC- Link, EtherNet/IP, EtherCAT				

^{*1:}Dimension is varied due to robot types

# Safety & Reliability

### Industrial Standards Conformance for Safety and Environment

The FANUC Robot i series is manufactured at fully automated and robotized factories under strict quality control, and meets ISO:9001 certifications.

The FANUC Robot i series is compliant with the European, American, Korean, etc. safety standards, and has been certified with the CE, NRTL and KCs marking (with options for each specification). TÜV marking and TÜV EMC marking are attached when the European specification for the robot is chosen.



# Maintenance & Support

#### Worldwide Customer Service

FANUC offers customer service and support anywhere in the world through subsidiaries and affiliates. FANUC prides itself in providing the highest quality service with the quickest response time at the nearest location to you.



### FANUC ACADEMY

FANUC ACADEMY offer a variety of intensive robot training courses, from introductory to advanced knowledge and skills for teaching, operation, engineering and maintenance of FANUC robots and their applications. Hands-on training provides your employees with the skills needed to operate and maintain your factory automation.

# CORPORATION

Headquarters Oshino-mura, Yamanashi 401-0597, Japan Phone: 81-555-84-5555 Fax: 81-555-84-5512 https://www.fanuc.co.jp Phone: 1-248-377-7000

Phone: 1-248-377-7000 Phone: 352-72777-1 Phone: 86-21-5032-7700 Phone: 82-55-278-1200 Phone: 886-4-2359-0522 Phone: 91-80-2852-0057 Phone: 65-6567-8566

Overseas Affiliated Companies FANUC America Corporation
FANUC Europe Corporation, S.A.
SHANGHAI-FANUC Robotics CO., LTD. KOREA FAINUC CORPORATION
TAIWAN FANUC CORPORATION
TAIWAN FANUC CORPORATION
FANUC INDIA PRIVATE LIMITED
FANUC SINGAPORE PTE. LTD.
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PT. FANUC INDONESIA FANUC OCEANIA PTY. LIMITED FANUC SOUTH AFRICA (PROPRIETARY) LIMITED 3900 West Hamlin Boad, Bochester Hills, MI 48309-3253, LLS A rue Benedikt Zender, L-6468 Echternach, Grand-Duché de Luxembourg b. 1500 Fulian Road, Baoshan Area, Shanghai, China

No. 1500 Fulian Road, Baoshan Area, Shanghai, China
101, Wanam-ro(st), Seongsangu, Changwon-si, Gyeongsangnam-do, 642-290 Republic of Korea
No. 10, 16th Road, Taichung Industrial Park, Taichung, Taiwan
41-A, Electronics City, Bangalore, 560 100, India
No. 1 Teban Gardens Crescent, Singapore 608919, Singapore
1301 Pattanakam Road, Kwaeng Suanluang, Khet Suanluang, Bangkok 10250 Thailand
No. 22, Persiaran Astana / KU 2, Bandar Bukit Raja, 41050 Klang,
Selangor Darul Ehsan, Malaysia
JL. Boulevard Bukit Gading Raya Blok R, Jakarta 14240 Indonesia
10 Healey Circuit, Huntingwood, NSW 2148, Australia
17 Loper Ave, Agroport Industrial Ests, Snartan Ext 2 PO Ray 219; Isanda 1600 Republic of South Africa

17 Loper Ave. Aeroport Industrial Ests, Spartan Ext.2 P.O.Box 219, Isando 1600, Republic of South Africa

Phone: 60-3-3082-1222 Phone: 62-21-4584-7285 Phone: 61-2-8822-4600 Phone: 27-11-392-3610

Phone: 66-2-714-6111

Fax: 352-7/4-7/051 Fax: 352-727777-403 Fax: 86-21-5032-7711 Fax: 82-55-284-9826 Fax: 886-4-2359-0771 Fax: 91-80-2852-0051 Fax: 65-6566-5937 Fax: 66-2-714-6120

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^{*2:}For the correspondence between robot models and controller, please check the description of each robot models.

^{*3:}This controller is an open air type, and should be installed in a "Pollution degree 2" environment regulated by IEC 60664-1, IEC/UL61010-1. "Pollution degree 2" means a clean, office-like environment.

^{*4:}Overvoltage Category II per IEC 60664-1. Overvoltage Category III per IEC/UL 61010-1.